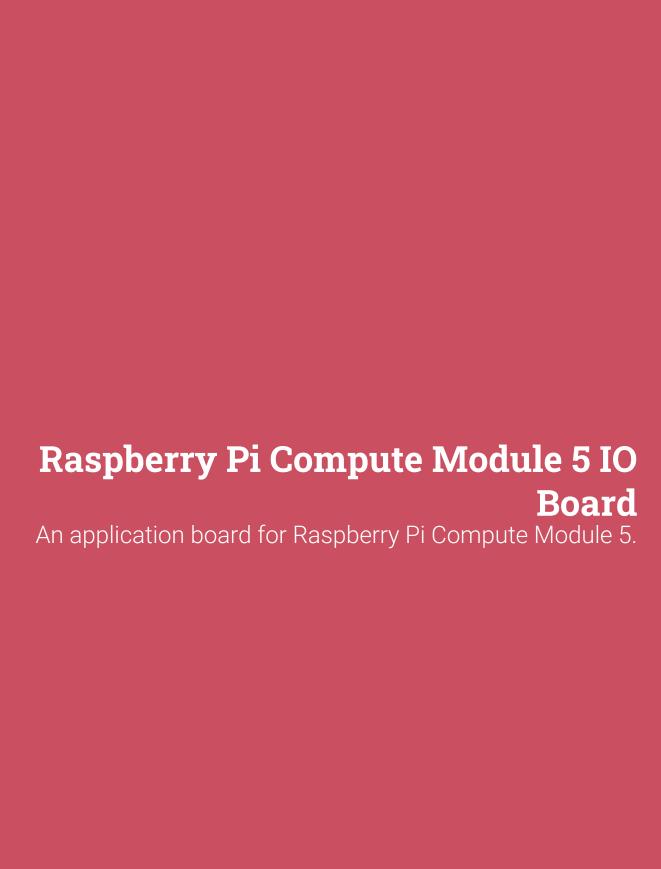


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### Colophon

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build-date: 2024-11-27 build-version: b971495-clean

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## **Chapter 1. Introduction**

Figure 1. Render of the Raspberry Pi Compute Module 5 IO Board.



The Raspberry Pi Compute Module 5 IO Board (CM5IO) is designed to assist in the development of products that make use of Raspberry Pi Compute Module 5. The Raspberry Pi Compute Module 5 IO Board contains many of the interfaces that Raspberry Pi 5 has, and for general usage you should refer to the Raspberry Pi 5 documentation. The CM5IO has been designed as both a reference design for CM5 or to be used directly as a product with the possible addition of M.2 M Key cards and Raspberry Pi HATs.

Chapter 1. Introduction

### **Chapter 2. Features**

- · Accepts the complete range of CM5 modules
- External +5v USB-C PSU
- Power button to wakeup and shutdown the CM5
- 2 × full-size HDMI 2.0 connectors
- Gigabit Ethernet RJ45 with PoE support
- 2 × USB 3 sockets
- microSD card socket for CM5Lite modules
- M.2 M key PCIe socket
- four-pin JST-SH PWM fan connector
- 2 × MIPI DSI/CSI-2 FPC connectors (22-pin 0.5mm pitch cable)
- HAT footprint with 40-pin GPIO connector
- PoE header
- · RTC battery socket
- · Jumpers to disable features such as eMMC boot, EEPROM write, the power button, and the USB OTG connection

#### 2.1. CM5 module connectors

The two CM5 module connectors are positioned so the on-board wireless antenna is at the edge of the board for best wireless performance.

#### 2.2. PSU input

The main PSU input (J11) is a standard USB-C connector. By default, the Raspberry Pi Compute Module 5 IO Board attempts to negotiate 5V @ 5A. You can power Raspberry Pi Compute Module 5 IO Board with a standard Raspberry Pi 5 power supply. If the Raspberry Pi Compute Module 5 IO Board doesn't negotiate 5A, CM5 will display a warning; this can be disabled. The exact power consumption greatly depends on the processor load and peripherals plugged into Raspberry Pi Compute Module 5 IO Board.

If you want to supply an external +5V supply to the board, this can be done via 38.

#### 2.3. Power Button

The power button replicates the function of the button on the Raspberry Pi 5. A short press brings up the shutdown menu. Another press powers the system down. A long press forces the system to power down. A short press from a previously shutdown system boots the system.

2.1. CM5 module connectors

#### 2.4. Dual full-size HDMI 2.0 connectors

CM5 does most of the interfacing required for the HDMI interface so that most signals are directly connected to the CM5 board. HDMI connectors require a +5V supply, which is provided on the Raspberry Pi Compute Module 5 IO Board via a current-limited switch.

#### 2.5. Gigabit Ethernet RJ45

The Raspberry Pi Compute Module 5 IO Board uses a standard 1:1 Ethernet magjack, which supports PoE as well. Additional ESD protection is provided on the Raspberry Pi Compute Module 5 IO Board, since this is typically needed for PoE applications. The PoE signals from the RJ45 connector are connected to J9. Typically, a PoE HAT supplies +5V to the Raspberry Pi Compute Module 5 IO Board.

#### 2.6. USB 3.0 Ports

The Raspberry Pi Compute Module 5 IO Board has two USB 3.0 Ports.

There is an internal current limit switch to provide VBUS to the USB connectors. The current limit is set to approximately 1.6A.

#### 2.7. USB Type C connector (Data)

The USB Type C (USB-C) connector enables Raspberry Pi Compute Module 5 IO Board updates via rpiboot. The USB-C port on the host computer must supply ample current to power the Raspberry Pi Compute Module 5 IO Board. If the computer isn't capable, use a powered USB hub.

#### 2.8. microSD card socket



For use only with CM5Lite modules.

The microSD card socket is a push-push socket. To release the microSD card, gently push on the card to unlock it.

#### 2.9. M.2 M-Key socket

The M.2 M-Key slot is designed for standard M.2 M key cards. You should ensure that there is a suitable OS driver for your card. Typically this connector is used with NVMe drives.

By default, the PCle port supports PCle Gen  $2 \times 1$  (5Gbps). PCle Gen  $3 \times 1$  (8Gbps) is possible, but experimental and therefore unsupported.

#### 2.10. Fan connector

Raspberry Pi Compute Module 5 IO Board uses the same fan connector as the Raspberry Pi 5. As a result, you can use any fans that work with Raspberry Pi 5.

NOTE: If the Raspberry Pi Compute Module 5is powered down the FAN will come on as the Fan PWM pin is not longer driven. If you are designing a board and this is undesirable then the Fan could instead be powered form the USB VBUS enable from U6 as when the Raspberry Pi Compute Module 5 is shutdown the VBUS\_EN is pulled low and so VBUS is shutdown.

# 2.11. MIPI Interface connectors (22-pin 0.5mm pitch cable)

There are two 4-lane MIPI DSI/CSI-2 connectors. CAM/DISP 0 supports both displays or cameras. CAM/DISP 0 supports using a signal to power down the camera to save power. CAM/DISP 1 typically needs two jumpers fitting to J6 to route the I2C signals form the GPIO connector to the camera connector. CAM/DISP 1 can be be used with displays and cameras. If it is used with a camera, it isn't possible to power down the camera.

#### 2.12. Raspberry Pi HAT connector

The Raspberry Pi Compute Module 5 IO Board has a standard Raspberry Pi 40-way HAT connector. Mounting holes are also provided so that standard HATs may be used.

#### 2.13. Real time clock Battery.

A battery socket is provided for a CR2032 battery. Batteries typically last for 5 years.

#### 2.14. Jumpers

#### 2.14.1. R4/R5 Vref voltage selection

By default the Raspberry Pi Compute Module 5 IO Board sets the CM5 IO voltage to +3.3V via R5. Moving R5 to R4 sets the IO voltage on CM5 to +1.8V. Moving the resistor requires the use of a soldering iron.



Only one of R4 or R5 may be fitted at any one time.

#### 2.14.2. J6 CSI0 DSI0 I2C enable

2.10. Fan connector

#### NOTE

For the J6 jumpers, if either CAM/DISP 1 is used then both jumpers must be fitted to route the I2C bus to the connectors.

#### Table 1. J2 jumpers

Pin	Function
1-2	nRPIB00T - if fitted, forces USB booting (useful if the eMMC becomes corrupted)
3-4	EEPROM_nWP - if fitted, write-protects the EEPROM on CM5
6	SYNC_OUT - IEEE1588 timing pin. (can be configured as input)
12	PMIC_ENABLE
13-14	Connect a push button to wakeup or shutdown CM5.

#### Table 2. J3 ( not fitted by default )

Pin	Function
1	WL_nDIS - when connected to ground the wireless interface will be disabled
2	GND - ground
3	BT_nDIS - when connected to ground the Bluetooth interface will be disabled

#### 2.15. LEDs

#### Red LED

This LED duplicates the function of the red LED on Raspberry Pi 5.

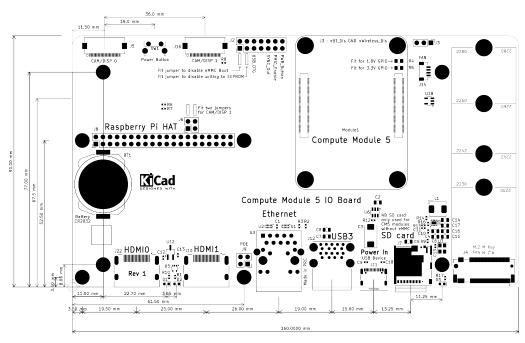
#### Green LED

This LED duplicates the function of the green LED on Raspberry Pi 5.

2.15. LEDs

# Chapter 3. Mechanical diagram

Figure 2. Mechanical diagram of the Raspberry Pi Compute Module 5 IO Board.



#### **1** NOTE

For additional information see the CM5 design files.

# Chapter 4. Circuit diagram

Figure 3. Top level

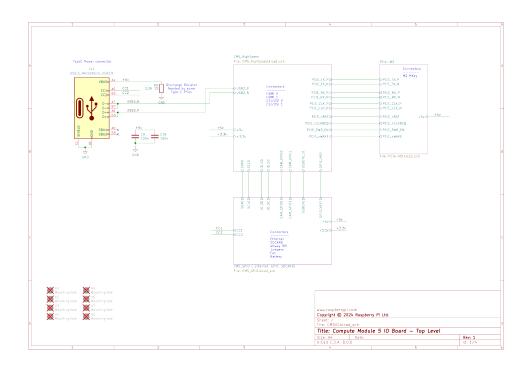


Figure 4. CM5 high speed

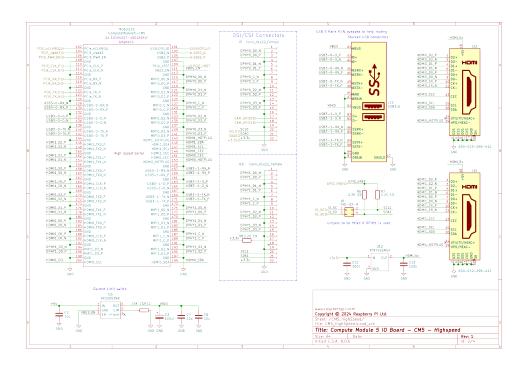


Figure 5. CM5 GPIO

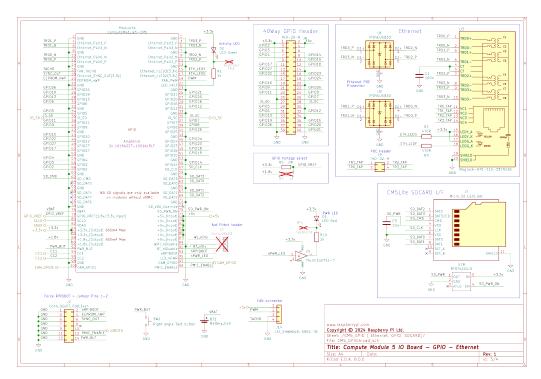
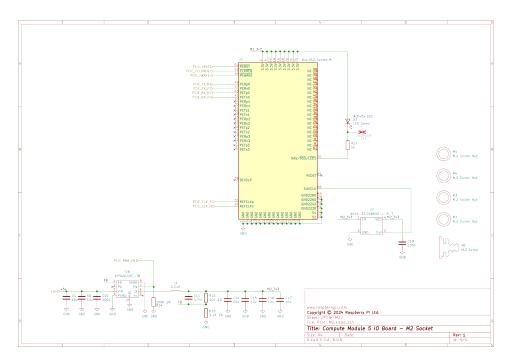


Figure 6. M.2 connector



# Appendix A: Mean Time Between Failure (MTBF)

Table 3. Mean time between failure for Raspberry Pi Compute Module 5 IO Board

Model	Mean Time Between Failure Ground Benign (Hours)	Mean Time Between Failure Ground Mobile (Hours)
Raspberry Pi Compute Module 5 IO Board	131 000	15 000

#### Ground, benign

Applies to non-mobile, temperature and humidity controlled environments readily accessible to maintenance; includes laboratory instruments and test equipment, medical electronic equipment, business and scientific computer complexes.

#### Ground, mobile

Assumes levels of operational stress well above normal domestic or light industrial use, without temperature, humidity or vibration control: applies to equipment installed on wheeled or tracked vehicles and equipment manually transported; includes mobile and handheld communications equipment.

# Appendix H: Documentation Release History

#### **27 November 2024**

• Initial release.

27 November 2024 12



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